

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings of claims in the application:

**Listing of Claims:**

1-40. (canceled)

41. (currently amended) A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional user-specified basis function including overlapping portions that are disposed at a plurality of locations and overlap with one another to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional user-specified basis function to obtain a distribution of the overlapping portions that are disposed at the plurality of locations, each overlapping portion representing a two-dimensional treatment portion to be applied to a tissue and combined with other overlapping portions to achieve the three-dimensional target profile for treatment of the tissue according to the distribution obtained from the fitting.

42. (original) The method of claim 41 wherein the three-dimensional profile has symmetry with respect to a two-dimensional section oriented radially from an axis of symmetry and extending in a generally circular treatment pattern around the axis.

43. (currently amended) [[The method of claim 42]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the three-dimensional profile has symmetry with respect to a two-dimensional section oriented radially from an axis of symmetry and extending in a generally circular treatment pattern around the axis;

wherein the overlapping portions are generally circular, and the two-dimensional basis function comprises discrete basis functions each representing a coverage angle of one of the overlapping portions as a function of a distance from the axis of symmetry.

44. (original) The method of claim 41 wherein the three-dimensional profile has symmetry with respect to a two-dimensional section oriented normal across a generally straight treatment pattern.

45. (currently amended) [[The method of claim 44]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the three-dimensional profile has symmetry with respect to a two-dimensional section oriented normal across a generally straight treatment pattern;

wherein the overlapping portions are generally circular, and the two-dimensional basis function comprises discrete basis functions each representing a depth of one of the overlapping portions as a function of a distance from the axis of symmetry.

46-56. (canceled)

57. (currently amended) The method of claim 41 wherein the basis function includes  $M$  discrete basis functions representing  $M$  overlapping portions.

58. (currently amended) [[The method of claim 57]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the basis function includes  $M$  discrete basis functions representing  $M$  overlapping portions;

wherein the  $M$  discrete basis functions represent  $M$  overlapping portions across a treatment zone length representing the length across a generally two-dimensional section which is oriented normal across a generally straight treatment pattern or which is oriented radially across a generally circular treatment pattern.

59. (previously presented) The method of claim 58 wherein the overlapping portions are generally circular and have a generally uniform energy profile.

60. (previously presented) The method of claim 59 wherein

(A) for a treatment profile having a generally uniform two-dimensional section oriented normal across a generally straight treatment pattern, the discrete basis functions represent the two-dimensional section as

$$X_i(x_j) = y_i(x_j) = \sqrt{(s/2)^2 - (x_j - x_{0i})^2} \text{ or}$$

(B) for a treatment profile having a generally uniform two-dimensional section oriented radially across a generally circular treatment pattern, the discrete basis functions represent the two-dimensional section as

$$X_i(x_j) = \theta_i(x_j) = \cos^{-1} \left( \frac{x_j^2 + x_{0i}^2 - (s/2)^2}{2 \cdot x_{0i} \cdot x_j} \right)$$

where

$s$  is the diameter of the overlapping portion;

$j = 1, \dots, N$ ;

$x_j$  is a reference  $x$ -coordinate for the two-dimensional section measured from an optical axis of the cornea of a  $j^{\text{th}}$  evaluation point for the center of the overlapping portion;

$x_{0i}$  is an  $x$ -coordinate for a center of an  $i^{\text{th}}$  overlapping portion;

$(x_{0i} - s/2) \leq x_j \leq (x_{0i} + s/2)$ ;

$y_i(x_j)$  is a depth of the  $i^{\text{th}}$  basis function for the generally straight treatment pattern;

and

$\theta_i(x_j)$  is a coverage angle of the  $i^{\text{th}}$  basis function for the generally circular treatment pattern.

61. (previously presented) The method of claim 60 wherein  $x_{0i}$  is specified for  $M$  number of equally spaced overlapping portions as  $x_{0i} = i * [(L - s + e) / M]$ ,

where

$L$  is the treatment zone length;

$e$  is an extended zone; and

$i = 1, \dots, M$ .

62. (previously presented) The method of claim 61 wherein  $e$  is set to about 0.1 to about 0.5 mm.

63. (currently amended) [[The method of claim 57]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the basis function includes  $M$  discrete basis functions representing  $M$  overlapping portions;

wherein  $M$  is equal to about 7 to about 97.

64. (currently amended) ~~The method of claim 57 further comprising~~ A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions, wherein the basis function includes  $M$  discrete basis functions representing  $M$  overlapping portions; and

refitting the target function with the basis function by varying the number of overlapping portions  $M$  to iterate for a best fit.

65. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the target function is:

(A) for myopia and myopic cylinder,

$$f(x_j) = \sqrt{R_1^2 - x_j^2} - \sqrt{\left(\frac{R_1(n-1)}{n-1+R_1D}\right) - x_j^2} + C \text{ or}$$

(B) for hyperopia and hyperopic cylinder,

$$f(x_j) = R_1 - \frac{R_1(n-1)}{n-1+R_1D} - \sqrt{R_1^2 - x_j^2} + \sqrt{\left(\frac{R_1(n-1)}{n-1+R_1D}\right) - x_j^2} \text{ or}$$

(C) for phototherapeutic keratectomy,

$$f(x_j) = d;$$

where

$$0 \leq x_j \leq (L - \text{shift});$$

$$j = 0, 1, \dots, N-1;$$

$$C = \sqrt{R_1^2 - s^2/4} + \sqrt{\left(\frac{R_1(n-1)}{n-1+R_1D}\right) - s^2/4};$$

$x_j$  is an  $x$ -coordinate measured from an optical axis of the cornea of the  $j^{\text{th}}$  evaluation point for the center of the overlapping portion;

$s$  is the diameter of the overlapping portion;

$R_1$  is the anterior radius of curvature of the cornea in meters;

$R_2$  is the final anterior radius of curvature of the cornea in meters;

$n = 1.377$  is the index of refraction of the cornea;

$D$  is the lens power of the overlapping portion in diopters;

$L$  is the treatment zone length representing the length across a generally uniform section which is oriented normal across a generally straight treatment pattern for myopic or hyperopic cylinders, or which is oriented radially across a generally circular treatment pattern for myopia or hyperopia;

*shift* is the amount of emphasis shift; and

$d$  is a constant depth.

66. (previously presented) The method of claim 65 wherein the shift is about 0 to about 0.2.

67. (previously presented) The method of claim 65 wherein  $x_j = j * [(L - shift) / N]$ .

68. (previously presented) The method of claim 65 wherein the basis function includes  $M$  discrete basis functions representing  $M$  overlapping portions, and wherein fitting the target function with the basis function comprises solving the following equation for coefficients  $a_i$  representing treatment depth for the  $i^{\text{th}}$  overlapping portion:

$$f(x_j) = \sum_{i=1}^M a_i X_i(x_j)$$

where

$X_i(x_j)$  is the  $i^{\text{th}}$  basis function; and

$i = 1, \dots, M$ .

69. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein fitting the target function and the basis function comprises specifying a deviation for each of the  $N$  discrete evaluation points.

70. (previously presented) The method of claim 69 further comprising refitting the target function with the basis function by varying the deviations to iterate for a best fit.

71. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein fitting the target function and the basis function comprises evaluating closeness of the fit and repeating the fitting step if the closeness does not fall within a target closeness.

72. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the target function and the basis function are fitted using a least square fit.

73. (currently amended) ~~The method of claim 41 further comprising~~ A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions; and



refitting the target function with the basis function by varying the size of at least one of the overlapping portions to iterate for a best fit.

74. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the overlapping portions have different sizes.

75. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the target function and the basis function are fitted using a simulated annealing process.

76. (currently amended) ~~The method of claim 41 further comprising~~ A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions; and

specifying a merit function representing an error of fit between the target function and the basis function; and minimizing the merit function.

77. (currently amended) ~~The method of claim 41 further comprising~~ A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions; and

refitting the target function with the basis function by selecting an overlapping portion location and varying the characteristics of the overlapping portion at the selected location to iterate for a best fit.